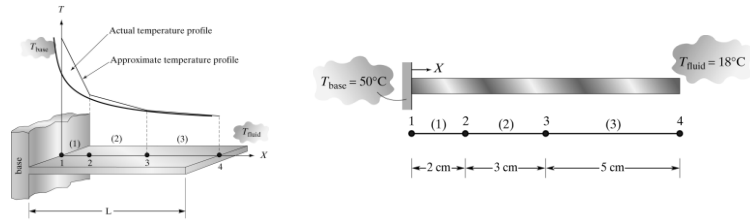
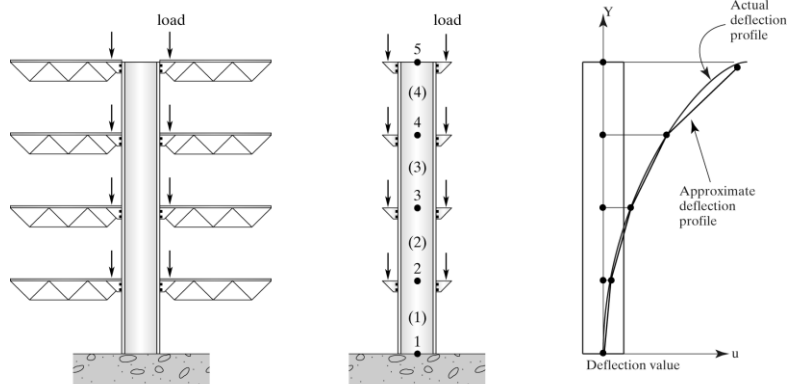


Chap. 3 One-Dimensional Elements



1-D Elements: A Column

- Columns: Commonly used to support loads from various floors of multi-story buildings.

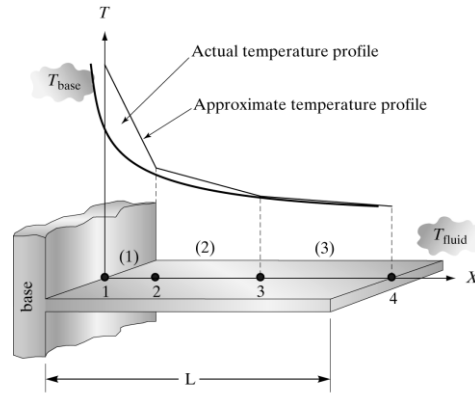


1-D Elements: Linear Elements

□ 1-D Heat Transfer of a Fin

- Fins: Commonly used in a variety of engineering applications to enhance cooling
- Ex) Engine heads, heat sinks in electronic equipment, heat exchangers, etc.
- The temperature profile on a fin surface can be assumed as 1-dimensional (3 1-d elements)
- Linear temperature distribution

(1)



1-D Elements: Linear Elements

□ 1-D Heat Transfer of a Fin

- The element's end conditions

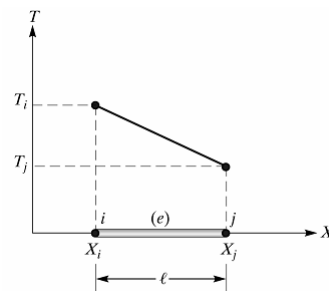
$$\begin{aligned} X = X_i &\rightarrow T = T_i \\ X = X_j &\rightarrow T = T_j \end{aligned} \quad (2)$$

- Substituting (2) into (1)

$$T_i = c_1 + c_2 X_i \quad T_j = c_1 + c_2 X_j \quad (3)$$



$$T^{(e)} = \frac{T_i X_j - T_j X_i}{X_j - X_i} + \frac{T_j - T_i}{X_j - X_i} X \quad \Rightarrow$$



□ Shape Function

- ◆ 1-d linear shape function

$$T^{(e)} = \underbrace{\left(\frac{X_j - X}{X_j - X_i} \right)}_{S_i} T_i + \underbrace{\left(\frac{X - X_i}{X_j - X_i} \right)}_{S_j} T_j \quad \text{where}$$

- ◆ Temperature distribution in terms of the shape f'ns

- ◆ Cf) For a structural example

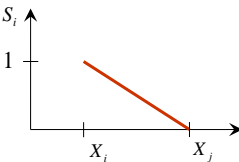
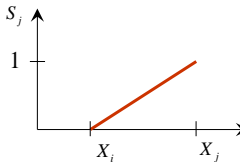
$$u^{(e)} = [S_i \quad S_j] \begin{Bmatrix} u_i \\ u_j \end{Bmatrix} \quad \Rightarrow \quad \Psi^{(e)} = [S_i \quad S_j] \begin{Bmatrix} \Psi_i \\ \Psi_j \end{Bmatrix} \quad (\text{general form})$$

□ Shape Function: Characteristics

- ◆ Has a value of unity at its corresponding node and has a zero at the other nodes (see the next slide in detail)
- ◆ In an element, the shape functions add up to a value of unity
- ◆ The sum of derivatives with respect to X is zero

1-D Elements: Linear Elements

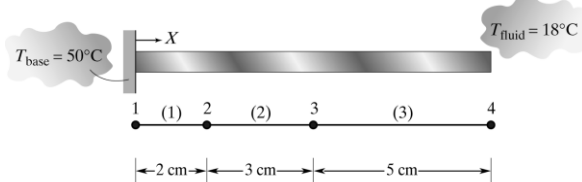
□ Shape Function: Characteristics

	S_i	S_j
Node i	$S_i _{X=X_i} = \frac{X_j - X}{\ell} \Big _{X=X_i} = \frac{X_j - X_i}{\ell} = 1$	$S_j _{X=X_i} = \frac{X - X_i}{\ell} \Big _{X=X_i} = \frac{X_i - X_i}{\ell} = 0$
Node j	$S_i _{X=X_j} = \frac{X_j - X}{\ell} \Big _{X=X_j} = \frac{X_j - X_j}{\ell} = 0$	$S_j _{X=X_j} = \frac{X - X_i}{\ell} \Big _{X=X_j} = \frac{X_j - X_i}{\ell} = 1$
Shape		

1-D Elements: Linear Elements

□ Shape Function: Example

$$\begin{Bmatrix} T_1 \\ T_2 \\ T_3 \\ T_4 \end{Bmatrix} = \begin{Bmatrix} 50 \\ 41 \\ 34 \\ 20 \end{Bmatrix} \text{ } ^\circ\text{C}$$



• Temperature at $X = 4 \Rightarrow$ element (2)

• Temperature at $X = 8 \Rightarrow$ element (3)

1-D Elements: Quadratic Elements

□ 1-D Heat Transfer of a Fin

- Quadratic approximation
- The element's end conditions
 - $T = T_i$ at $X = X_i$
 - $T = T_j$ at $X = X_j$
 - $T = T_k$ at $X = X_k$
- Substituting (5) into (4)

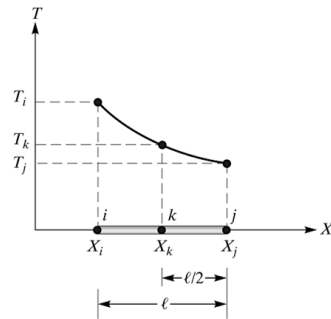
$$T_i = c_1 + c_2 X_i + c_3 X_i^2$$

$$T_j = c_1 + c_2 X_j + c_3 X_j^2$$

$$T_k = c_1 + c_2 X_k + c_3 X_k^2$$

(4)

(5)

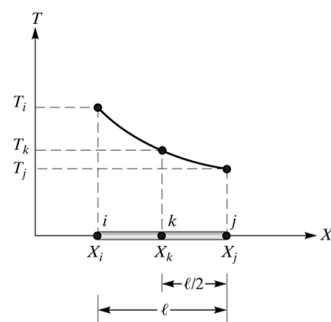


1-D Elements: Quadratic Elements

□ Shape Function

- 1-d linear shape function
- Temperature distribution in terms of the shape f'ns

$$T^{(e)} = S_i T_i + S_j T_j + S_k T_k$$



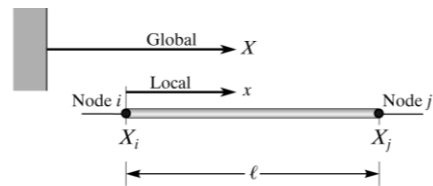
Coordinates: Global, Local, Natural

Global Coordinate System

- Needed to represent the location of each node and the orientation of each element
- Convenient to apply boundary conditions and loads (in terms of their global components)
- Solutions (eg. nodal displacements) is represented wrt. the global directions

Local Coordinate System

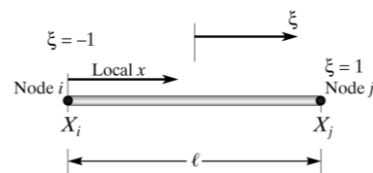
- Advantageous in computing integrals, especially the integrals contain products of shape fn's
- Usually started from 0: $0 \leq x \leq \ell$
- Shape fn's in terms of the local coordinates



Coordinates: Global, Local, Natural

Natural Coordinate System

- Local coordinates in a dimensionless form
- Normalized between -1 to 1:
- Linear shape fns in terms of the natural coordinate
- Temperature distribution over an element of a 1-d fin



Ex 3.3 (p. 133)

- Transformation with other coordinates

Global coord. $X (X_i \leq X \leq X_j)$

$$\xi = -1, T = T_i \quad \xi = 1, T = T_j$$

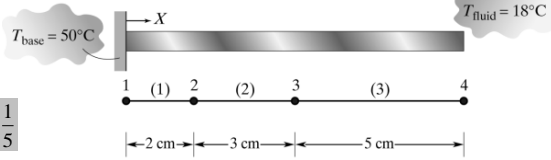
Local coord. $x (0 \leq x \leq \ell)$

□ Shape Function: Example

$$\begin{Bmatrix} T_1 \\ T_2 \\ T_3 \\ T_4 \end{Bmatrix} = \begin{Bmatrix} 50 \\ 41 \\ 34 \\ 20 \end{Bmatrix} \text{ } ^\circ\text{C}$$

Temperature at $X = 8$
=> element (3)

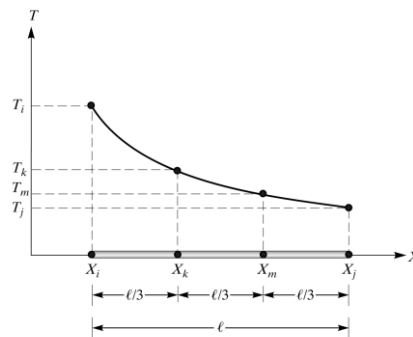
$$\xi = \frac{2x}{\ell} - 1 = \frac{2 \times 3}{5} - 1 = \frac{1}{5}$$



- Using shape functions based on the global coordinate
- Using shape functions based on the local coordinate
- Using shape functions based on the natural coordinate

1-D Natural Quadratic Shape Function

1-D Natural Cubic Shape Function



□ Gauss-Legendre Quadrature

- ◆ Integral: The sum of the product of certain weighting coefficients and the value of functions at some selected point (efficient in the natural coordinate system)

- ◆ Determination of the weighting coefficient :

$$x = c_0 + c_1 \lambda \quad [a, b] \Rightarrow [-1, 1]$$

$$a = c_0 + c_1(-1) \quad b = c_0 + c_1(1) \quad \Rightarrow$$

$$x = \frac{(b+a)}{2} + \frac{(b-a)}{2} \lambda \quad dx = \frac{(b-a)}{2} d\lambda$$



□ Two-Point Gauss-Legendre Quadrature

- ◆ $n = 2 \Rightarrow 4$ unknowns $w_1, w_2, \lambda_1, \lambda_2$

Ex 3.5~6 (p. 137~139)

- ◆ Legendre polynomials: $f(\lambda) = 1, \lambda, \lambda^2, \lambda^3$

$$w_1 f(\lambda_1) + w_2 f(\lambda_2) = \int_{-1}^1 1 d\lambda = 2$$

$$w_1 f(\lambda_1) + w_2 f(\lambda_2) = \int_{-1}^1 \lambda d\lambda = 0 \quad \Rightarrow$$

$$w_1 f(\lambda_1) + w_2 f(\lambda_2) = \int_{-1}^1 \lambda^2 d\lambda = \frac{2}{3}$$

$$w_1 f(\lambda_1) + w_2 f(\lambda_2) = \int_{-1}^1 \lambda^3 d\lambda = 0$$

